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Tullock Contests with Asymmetric Information^{*/}

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Tullock Contests with Asymmetric Information

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Abstract

Under standard assumptions about players' cost functions, we show that a Tullock contest with asymmetric information has a pure strategy equilibrium. Moreover, when players have a common value and a common state independent linear cost function, a two player Tullock contest in which one player has an information advantage has a unique equilibrium. In this equilibrium both players exert the same expected effort, although the player with information advantage has a greater payoff and wins the prize less frequently than his opponent. When there are more than two players in the contest, an information advantage leads to higher payoffs, but the other properties of equilibrium no longer hold.

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1 Introduction

In a *Tullock contest* – Tullock (1980) – a player’s probability of winning the prize is the ratio of the effort he exerts and the total effort exerted by all the players. Baye and Hoppe (2003) have identified a variety of economic settings (rent-seeking, innovation tournaments, patent races) which are strategically equivalent to a Tullock contest. Tullock contests also arise by design, e.g., sport competition, internal labor markets. A number of studies have provided an axiomatic justification to such contests, see, e.g., Skaperdas (1996) and Clark and Riis (1998)).

There is an extensive literature studying Tullock contests and its variations under complete information about the players’ value of the prize and their cost of effort. Perez-Castrillo and Verdier (1992), Baye Kovenock and de Vries (1994), Szidarovszky and Okuguchi (1997), Cornes and Hartley (2005), Yamazaki (2008) and Chowdhury and Sheremeta (2009) study existence and uniqueness of equilibrium. Skaperdas and Gan (1995), Glazer and Konrad (1999), Konrad (2002), Cohen and Sela (2005) and Franke *et al.* (2011), study the effect on the players’ behavior of changes in the payoff structure, and Schweinzer and Segev (2012) and Fu and Lu (2013) study optimal prize structures. See Konrad (2008) for a general survey.

In this paper we study Tullock contests under asymmetric information (i.e., when player’s value for the prize and/or their cost of effort is private information), a topic seldom investigated in the literature. Fey (2008) and Wasser (2013) have recently provided an analysis of rent-seeking games under incomplete information. More closely related to our work is Warneryd (2003), which we discuss below.

In our setting, each player’s value for the prize as well as his cost of effort depend on the state of nature. The set of states of nature is finite. Players have a common prior belief, but upon the realization of the state of nature, and prior to taking action, each player observes some event that contains the realized state of nature. The information of each player at the moment of taking action is therefore described by a partition of the set of states of nature. (Jackson (1993) and Vohra (1999) have shown that this representation is equivalent to Harsanyi model of a Bayesian game using players’ types.) A contest is therefore described by a set of players, a probability space describing players’ prior uncertainty and beliefs, a collection of partitions of the state space describing the players’ information, a collection of state dependent

functions describing the players' values and costs, and a success function specifying the probability distribution used to allocate the prize for each profile of efforts. We assume throughout that the players cost functions are continuously differentiable, strictly increasing and convex with respect to effort, and that the cost of exerting no effort is zero in every state. (In a similar framework, Einy et al. (2001, 2002), Forges and Orzach (2011), and Malueg and Orzach (2009, 2012) study common-value first- and second-price auctions.)

We show that a Tullock contest has a pure strategy Bayesian equilibrium. The proof involves constructing a sequence of equilibria of contests obtained from the original Tullock contest by truncating the action space so that it is a closed and bounded interval whose lower bound approaches zero from above. We show that any limit point of a sequence of equilibria of these contests (which have an equilibrium by Nash's Theorem) is an equilibrium of the original Tullock contest. A key step in the proof is to show that in any such limit point the total effort exerted by players is positive in every state of nature. (Hence this is also a property of the pure strategy equilibrium of the contest that we construct.) Our existence result applies whether players have private or common values and whether players' costs of effort is the same or different, and makes no presumption about the players' private information. Moreover, it extends to a general class of Tullock *like* contests which success function is formed as a ratio of the score given to each players' effort and the total scores given to all players, provided each player's score function is strictly increasing and concave. (Warneryd (2012) establishes existence of equilibrium for common value Tullock contests when there are two types of players, those that have complete information and those who only have the prior information, and investigates which players are active, i.e., make a positive effort, in equilibrium.)

Next we study Tullock contests in which players have a common value for the prize and a common state independent linear cost function, to which we refer simply as *common-value Tullock contests*. We consider first two-player common-value Tullock contests in which one of the players has an information advantage over his opponent (i.e., the partition of one player is finer than that of his opponent). We show that such contests have a unique (pure strategy) Bayesian equilibrium, which we characterize. In equilibrium both players exert the same expected effort. Moreover, both players

have a positive expected payoff, although the payoff of the player with an information advantage is greater than that of his opponent. Interestingly, the player with an information advantage wins the prize less frequently (i.e., with a smaller ex-ante probability) than the uninformed player. We also examine how players' information affects the effort they exert and their payoffs. Assuming that the distribution of the players' value for the prize is not too dispersed, we show that when one player is better informed than the other the total effort exerted by players and the share of the total surplus they capture is larger than when both players have the same information.

In the same framework and under the same assumptions, Einy *et al.* (2013) characterize the unique equilibrium of a two-player common-value all-pay auction, which is in mixed strategies, and show that the expected payoff of the player with an information advantage is positive while the expected payoff of his opponent is zero, and that both the expected effort and the ex-ante probability of winning the prize are the same for both players. Using the results in Einy *et al.* (2013) and our results we study the relative effectiveness of Tullock contests and all-pay auctions to induce players to exert effort. We find that the sign of the difference in the total effort exerted by players in these contests is undetermined, and may be either positive or negative depending on the distribution of the players' value for the prize – see Example 1. (Fang (2002) and Epstein, Meale and Nitzan (2011) study the outcomes of Tullock contests and all-pay auction under complete information.)

Finally, we study whether our results for two-players common-value Tullock contests extend when there are more than two players in the contest. It turns out that our observation that the player with an information advantage obtains a greater payoff than his opponent holds generally in common-value Tullock contests: simply observing the formal equivalence between a common-value Tullock contest and an oligopoly with asymmetric information allows us to obtain this result as an implication of a theorem of Einy, Moreno and Shitovitz (2002) that shows that in any Cournot Bayesian equilibrium of an oligopolistic industry a firm's information advantage leads to greater profits. The other properties of equilibrium of two-player contests, however, do not hold in contests with more than two players: specifically, we show a three-player example in which two of the players have superior (and symmetric) information to that of the third player, in which the expected effort exerted by players differs. We

also provide an example of a contest in which all but one player have the same information and the remaining player has an information advantage, in which the ex-ante probability that the player with information advantage wins the prize is greater than that of any of the other players.

Our results for two-player common-value Tullock contests are closely related to those of Warneryd (2003), who studies a model in which the players common value is a continuous random variable. In particular, Warneryd (2003) shows that a Tullock contest in which one player observes the value and the other does not observe anything – the distribution of the value is common knowledge – has a unique equilibrium, which is interior, and obtains properties of this equilibrium which are akin to those we obtain. In our setting, when one of the players has an information advantage over the other, it can be assumed without loss of generality that one player observes the value while the other only has the common prior information. However, when the distribution of the common value is sufficiently disperse the unique equilibrium is a corner equilibrium. It turns out that some of the properties of the interior equilibrium do not hold when the equilibrium is not interior.

The rest of the paper is organized as follows: in Section 2 we describe the general setting. In Section 3 we establish that every Tullock contest has a pure strategy Bayesian equilibrium. Section 4 and 5 study common-value Tullock contests with two players, and with more players, respectively. Section 6 concludes. Long proofs are given in the Appendix.

2 The model

A group of players $N = \{1, \dots, n\}$, with $n \geq 2$, compete for a prize by choosing a level of *effort* on \mathbb{R}_+ . Players' uncertainty about the state of nature is described by a probability space (Ω, p) , where Ω is a finite set and p is a probability distribution over Ω describing the players' common prior belief about the realized state of nature. W.l.o.g. we assume that $p(\omega) > 0$ for every $\omega \in \Omega$. The private information about the state of nature of player $i \in N$ is described by a partition Π_i of Ω . Players compete for the prize. The value for the price of each player is described by a random variable $V_i : \Omega \rightarrow \mathbb{R}_{++}$, i.e., if $\omega \in \Omega$ is realized then player i 's ("private") value for the

prize is $V_i(\omega)$. The cost of effort of each player $i \in N$ is described by a function $c_i : \Omega \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$, which is continuously differentiable, strictly increasing and convex with respect to effort x_i , and such that $c_i(\cdot, 0) = 0$ on Ω .

A contest starts by a move of nature that selects a state ω from Ω according to the distribution p . Every player $i \in N$ observes the element $\pi_i(\omega)$ of Π_i which contains ω . Then players simultaneously choose their effort levels $(x_1, \dots, x_n) \in \mathbb{R}_+^n$. The prize is awarded in a probabilistic fashion, according to a *success function* ρ , which for each profile of effort levels $x \in \mathbb{R}_+^n$ assigns the prize to players according to a probability distribution $\rho(x)$ in the n -simplex. Thus, the payoff of player $i \in N$, $u_i : \Omega \times \mathbb{R}_+^n \rightarrow \mathbb{R}$, is given for every $\omega \in \Omega$ and $x \in \mathbb{R}_+^n$ by

$$u_i(\omega, x) = \rho_i(x) V_i(\omega) - c_i(\omega, x_i). \quad (1)$$

Thus, a *contest* is described by a collection $(N, (\Omega, p), \{\Pi_i\}_{i \in N}, \{V_i\}_{i \in N}, \{c_i\}_{i \in N}, \rho)$.

In a contest, a pure strategy of player $i \in N$ is a Π_i -measurable function $X_i : \Omega \rightarrow \mathbb{R}_+$ (i.e., X_i is constant on every element of Π_i), that represents i 's choice of effort in each state of nature following the observation of his private information. We denote by S_i the set of strategies of player i , and by $S = \prod_{i=1}^n S_i$ the set of strategy profiles. For any strategy $X_i \in S_i$ and $\pi_i \in \Pi_i$, $X_i(\pi_i)$ stands for the constant value that $X_i(\cdot)$ takes on π_i . Also, given a strategy profile $X = (X_1, \dots, X_n) \in S$, we denote by X_{-i} the profile obtained from X by suppressing the strategy of player $i \in N$. Throughout the paper we restrict attention to pure strategies.

Let $X = (X_1, \dots, X_n)$ be a strategy profile. We denote by $U_i(X)$ the expected payoff of player i , which is given by

$$U_i(X) \equiv E[u_i(\cdot, (X_1(\cdot), \dots, X_n(\cdot)))].$$

For $\pi_i \in \Pi_i$, we denote by $U_i(X \mid \pi_i)$ the expected payoff of player i conditional on π_i , i.e.,

$$U_i(X \mid \pi_i) \equiv E[u_i(\cdot, (X_1(\cdot), \dots, X_n(\cdot))) \mid \pi_i].$$

An N -tuple of strategies $X^* = (X_1^*, \dots, X_N^*)$ is a Bayesian equilibrium if for every player $i \in N$, and every strategy $X_i \in S_i$

$$U_i(X^*) \geq U_i(X_{-i}^*, X_i); \quad (2)$$

or equivalently,

$$U_i(X^* \mid \pi_i) \geq U_i(X_{-i}^*, X_i \mid \pi_i) \quad (3)$$

for every $\pi_i \in \Pi_i$.

3 Existence of Equilibrium

Tullock contests are identified by a class of success functions ρ^T such that for $x \in \mathbb{R}_+^n \setminus \{0\}$ the probability that player $i \in N$ wins the prize is

$$\rho_i^T(x) = \frac{x_i}{\bar{x}}, \quad (4)$$

where $\bar{x} \equiv \sum_{k=1}^N x_k$ is the total effort exerted by the players. Theorem 1 establishes that under our assumptions a Tullock contest has a pure strategy equilibrium.

Theorem 1. *Every Tullock contest has a (pure) strategy Bayesian equilibrium.*

Note that Theorem 1 makes no presumption about the players' private information, and applies whether players have private or common values, and whether their costs of effort is the same or different. A direct implication of Theorem 1 is the existence of equilibrium for a general class of success functions. For this class of success functions, Szidarovszky and Okuguchi (1997) have established existence of a unique equilibrium when players have complete information.

Corollary 1. *Every contest such that the success function ρ is given for $x \in \mathbb{R}_+^n \setminus \{0\}$ and $i \in N$ by*

$$\rho_i(x) = \frac{g_i(x_i)}{\sum_{j=1}^n g_j(x_j)},$$

where for every $j \in N$ the function $g_j : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is strictly increasing and concave, has a Bayesian equilibrium.

Proof. Let $C = (N, (\Omega, p), \{\Pi_i\}_{i \in N}, \{V_i\}_{i \in N}, \{c_i\}_{i \in N}, \rho)$ be a contest satisfying the assumptions of Corollary 1 for (g_1, \dots, g_n) . The Tullock contest $(N, (\Omega, p), \{\Pi_i\}_{i \in N}, \{V_i\}_{i \in N}, \{\bar{c}_i\}_{i \in N}, \rho^T)$ where $\bar{c}_i(\cdot, \cdot) = c_i(\cdot, g_i^{-1}(\cdot))$ for every $i \in N$ and $\rho^T(0) = \rho(0)$ has a Bayesian equilibrium $X^* = (X_1^*, \dots, X_n^*)$ by Theorem 1. It is easy to see that $Y^* = (g_1^{-1} \circ X_1^*, \dots, g_n^{-1} \circ X_n^*)$ is a Bayesian equilibrium of C . ■

4 Two-Player Common-Value Tullock Contests

Henceforth we study contests in which players have a common value for the prize and a common state independent linear cost function, i.e., such that for all $i \in N$, $V_i = V$, and $c_i(\cdot, x) \equiv x$ on Ω . We refer to these contests as *common-value contests*, and they are described by a collection $(N, (\Omega, p), (\Pi_i)_{i \in N}, V, \rho)$. Let us index the set of states of nature as $\Omega = \{\omega_1, \dots, \omega_m\}$, write $p(\omega_k) = p_k$ and $V(\omega_k) = v_k$ for $k \in \{1, \dots, m\}$, and assume, w.l.o.g., that $0 < v_1 < v_2 < \dots < v_m$.

In this section we study two-player common-value Tullock contests in which player 2 has an information advantage over player 1 (i.e., such that Π_2 is finer than Π_1). Thus, we may assume w.l.o.g. that the only information player 1 has about the state is that described by the common prior, i.e., $\Pi_1 = \{\Omega\}$, whereas player 2 has perfect information about the state of nature, i.e., $\Pi_2 = \{\{\omega_1\}, \dots, \{\omega_m\}\}$. In such contests a strategy profile is a pair (X, Y) , where $X = (x, \dots, x) \in \mathbb{R}_+^m$ specifies player 1's unconditional effort x , and $Y = (y_1, \dots, y_m) \in \mathbb{R}_+^m$ specifies the effort of player 2 in each state of nature.

The following notation will be useful in characterizing the pure strategy Bayesian equilibria of a Tullock contest. For $k \in \{1, \dots, m\}$ write

$$A_k = \left(\sum_{s=k}^m p_s \sqrt{v_s} \right) \left(1 + \sum_{s=k}^m p_s \right)^{-1}. \quad (5)$$

Note that

$$A_1 = \frac{E(\sqrt{V})}{2}.$$

Lemma 1 establishes a key property of the mapping A .

Lemma 1. *If $\sqrt{v_{\bar{k}}} \geq A_{\bar{k}}$ for some $\bar{k} < m$, then $\sqrt{v_k} > A_k$ and $A_{\bar{k}} \geq A_k$ for all $k > \bar{k}$.*

Proposition 1 establishes that a two-player common-value Tullock contest in which player 2 has an information advantage has a unique pure strategy equilibrium which is easily identified. Let $k^* \in \{1, \dots, m\}$ be the smallest index such that $\sqrt{v_k} \geq A_k$. Since

$$\sqrt{v_m} > \frac{p_m}{(1 + p_m)} \sqrt{v_m} = A_m,$$

then k^* is well defined.

Proposition 1. *A two-player common-value Tullock contest in which player 2 has an information advantage has a unique Bayesian equilibrium (X^*, Y^*) given by $x^* = A_{k^*}^2$, $y_k^* = 0$ for $k < k^*$, and $y_k^* = A_{k^*}(\sqrt{v_k} - A_{k^*})$ for all $k \geq k^*$.*

Since by convention v_1 is the smallest possible value, then $\sqrt{v_1} \geq A_1 = E(\sqrt{V})/2$, and therefore $k^* = 1$, whenever the distribution of values is not too disperse; e.g., this inequality holds when $v_m \leq 4v_1$. When this is the case, then the unique equilibrium is interior. For future references we state this observation in Remark 2.

Remark 2. *Consider a two-player common-value Tullock contest in which player 2 has an information advantage. The unique Bayesian equilibrium is interior if and only if $\sqrt{v_1} \geq E(\sqrt{V})/2$, i.e., the distribution of values is not too disperse.*

Interestingly, when one player has superior information the expected effort exerted by players in the equilibrium of the contest is the same.

Proposition 2. *In a two-player common-value Tullock contest in which player 2 has an information advantage both players exert the same expected effort, i.e., $E(Y^*) = A_{k^*}^2 = x^* = E(X^*)$. Hence the expected total effort is $TE = E(X^*) + E(Y^*) = 2A_{k^*}^2$.*

Proof. By Proposition 1,

$$\begin{aligned}
E(Y^*) &= \sum_{s=1}^m p_s y_s^* \\
&= \sum_{s=k^*}^m p_s A_{k^*} (\sqrt{v_k} - A_{k^*}) \\
&= A_{k^*} \sum_{s=k^*}^m p_s \sqrt{v_k} - A_{k^*}^2 \sum_{s=k^*}^m p_s \\
&= A_{k^*}^2 \left(1 + \sum_{s=k^*}^m p_s \right) - A_{k^*}^2 \sum_{s=k^*}^m p_s \\
&= A_{k^*}^2. \blacksquare
\end{aligned}$$

In a two-player common-value Tullock contest in which player 2 has an information advantage the equilibrium probabilities that player 1 wins the prize when the state is ω_k is

$$\rho_{1k}^* := \rho_1^T(x^*, y_k^*) = \frac{A_{k^*}^2}{A_{k^*}^2 + A_{k^*}(\sqrt{v_k} - A_{k^*})} = \frac{A_{k^*}}{\sqrt{v_k}},$$

whereas the probability that player 2 wins the prize is $\rho_{2k}^* = 1 - \rho_{1k}^*$. Thus, the larger is the realized value of the prize, the smaller (larger) is the probability that player 1 (player 2) wins the prize, i.e., $\rho_{1k'}^* < \rho_{1k}^*$ and $\rho_{2k'}^* > \rho_{2k}^*$ for $k' > k \geq k^*$. Of course, the larger is the realized value of the prize, the larger is the effort of player 2, i.e.,

$$y_{k'}^* = A_{k^*} (\sqrt{v_{k'}} - A_{k^*}) > A_{k^*} (\sqrt{v_k} - A_{k^*}) y_k^*.$$

for $k' > k \geq k^*$. Also, for $k' > k \geq k^*$,

$$\rho_{1k'}^* v_{k'} = A_{k^*} \sqrt{v_{k'}} > A_{k^*} \sqrt{v_k} = \rho_{1k}^* v_k,$$

i.e., the larger is the realized value of the prize, the larger are the conditional expected payoffs of both players, and

$$\rho_{2k'}^* v_{k'} = \rho_{2k}^* v_{k'} > \rho_{2k}^* v_k = \rho_{2k}^* v_k,$$

i.e., the conditional expected payoff of player 2 is larger the larger is the realized value of the price. Write $\bar{\rho}_i^* = E(\rho_i^*)$ for the ex-ante probability that player i wins the prize. Proposition 3 establishes another interesting property of equilibrium.

Proposition 3. *In a two-player common-value Tullock contest in which player 2 has an information advantage the ex-ante probability that player 1 wins the prize is greater than that of player 2, i.e., $\bar{\rho}_1^* > \bar{\rho}_2^*$.*

Remark 3 states that under symmetric information each player exerts an expected effort equal to $E(V)/4$. (The proof of this result is straightforward, and is therefore omitted.)

Remark 3. *A two-player common-value Tullock contest in which players have symmetric information has a unique pure strategy equilibrium, which is symmetric and involves each player exerting an expected effort equal to $E(V)/4$.*

The surplus captured by the players in a contest is the difference between the expected (total) surplus $E(V)$ and the expected total effort they exert. In Proposition 4 below we show that when player 2 has an information advantage, in an interior equilibrium players exert less effort, and therefore capture a greater surplus, than when they are symmetrically informed.

Proposition 4. *Consider a two-player common-value Tullock contest in which player 2 has an information advantage. If the distribution of values is not too disperse, i.e., $\sqrt{v_1} \geq E(\sqrt{V})/2$, then the players' exert less effort and capture a greater share of the surplus than when both players have symmetric information.*

Proof. When player 2 has an information advantage, then $\sqrt{v_1} \geq E(\sqrt{V})/2$ implies that the equilibrium is interior by Remark 3, and therefore the expected total effort is $TE = 2A_1^2 = E(\sqrt{V})^2/2$ by Proposition 2. When players have symmetric information the expected total effort \overline{TE} is $\overline{TE} = E(V)/2$ by Remark 3. Then Jensen's inequality implies

$$\overline{TE} - TE = \frac{E(V)}{2} - \frac{E(\sqrt{V})^2}{2} > 0. \blacksquare$$

The contests arising in many economic and political applications are effectively an *all pay auction* either by design (e.g., sports or political competition) or by the nature of problem (e.g., a patent races). We conclude this section studying what can be said about the players' expected total effort in all pay auctions and Tullock contests.

A *common-value all pay auction* is a common-value contest in which the success function is given for $x \in \mathbb{R}_+^n$ by $\rho^{APA}(x) = 1/m(x)$ if $x_i = \max\{x_j\}_{j \in N}$, and $\rho^{APA}(x) = 0$ otherwise, where $m(x) = |\{k \in N : x_k = \max\{x_j\}_{j \in N}\}|$. Einy *et. al.* (2013) show that in unique equilibrium of a two-player common-value all pay auction in which player 2 has an information advantage over player 1 (i.e., Π_2 is finer than Π_1) the players' total expected effort is

$$TE^{APA} = 2 \sum_{s=1}^m p_s \left(\sum_{k=1}^{s-1} p_k v_k + \frac{1}{2} p_s v_s \right) = 2 \sum_{s=1}^m p_s \sum_{k=1}^{s-1} p_k v_k + \sum_{s=1}^m p_s^2 v_s.$$

Hence the difference between total efforts in an all pay auction and a Tullock contest is

$$\Delta := TE^{APA} - TE = 2 \sum_{s=1}^m p_s \sum_{k=1}^{s-1} p_k v_k + \sum_{s=1}^m p_s^2 v_s - 2A_{k^*}^2.$$

For simplicity, consider the case where there are only two states of nature, i.e., $m = 2$.

If the equilibrium of the Tullock contest is interior, then

$$\begin{aligned}
\Delta &= 2p_1p_2v_1 + (p_1^2v_1 + p_2^2v_2) - 2A_1^2 \\
&= 2p_1p_2v_1 + p_1^2v_1 + p_2^2v_2 - 2\frac{(p_1\sqrt{v_1} + p_2\sqrt{v_2})^2}{4} \\
&= 2p_1p_2v_1 + \frac{1}{2}(p_1\sqrt{v_1} - p_2\sqrt{v_2})^2 \\
&> 0.
\end{aligned}$$

Hence an all pay auction generates more effort than a Tullock contest. However, if the Tullock contest has a corner equilibrium, then

$$\begin{aligned}
\Delta &= 2p_1p_2v_1 + (p_1^2v_1 + p_2^2v_2) - 2A_2^2 \\
&= 2p_1p_2v_1 + p_1^2v_1 + p_2^2v_2 - 2\frac{(p_2\sqrt{v_2})^2}{(1+p_2)^2} \\
&= p_1v_1(1+p_2) - p_2^2v_2\left(\frac{2}{(1+p_2)^2} - 1\right).
\end{aligned}$$

Thus, Δ may be either positive or negative depending on the distribution of the players' common value – see Example 1 below. Thus, the level of effort generated by these two contests cannot be ranked in general.

The following example illustrates our findings.

Example 1. Let $m = 2$, $p_1 = 1 - p$, $v_1 = 1$, and $v_2 = v$, where $p \in (0, 1)$ and $v \in (1, \infty)$. Then $E(V) = 1 - p(1 - v)$, $E(\sqrt{V}) = 1 - p(1 - \sqrt{v})$, $A_1 = E(\sqrt{V})/2$, and $A_2 = p\sqrt{v}/(1 + p)$. If $v \leq (1 + p)^2/p^2$, then $\sqrt{v_1} = 1 \geq A_1$ and $k^* = 1$; otherwise $k^* = 2$.

In a Tullock contest in which player 2 observes the value but player 1 does not, the unique equilibrium is

$$X^* = (A_1^2, A_1^2), \quad Y^* = (A_1(1 - A_1), A_1(\sqrt{v} - A_1)),$$

and the total effort is $TE = 2A_1^2 = [1 - p(1 - \sqrt{v})]^2/2$ when $v \leq (1 + p)^2/p^2$. Otherwise, the unique equilibrium is

$$X^* = (A_2^2, A_2^2), \quad Y^* = (0, A_2(\sqrt{v} - A_2)),$$

and the total effort is $TE = 2A_2^2 = 2p^2v/(1 + p)^2$. If $v \leq (1 + p)^2/p^2$, then the ex-ante probability that player 1 wins the prize is

$$\bar{p}_1^* = (1 - p)A_1 + p\frac{A_1}{\sqrt{v}} = \frac{1}{2}(p + (1 - p)\sqrt{v})\frac{1 - p + p\sqrt{v}}{\sqrt{v}} \geq \frac{1}{1 + p} > \frac{1}{2}.$$

Otherwise, this probability is

$$\bar{p}_1^* = (1 - p) + p \frac{A_2}{\sqrt{v}} = (1 - p) + \frac{p^2}{1 + p} = \frac{1}{1 + p} > \frac{1}{2}.$$

Hence, consistently with Proposition 3 the uninformed player wins the prize more frequently than the informed player. Further, if $v \leq (1 + p)^2 / p^2$, then

$$\begin{aligned} 2[U_2(X^*, Y^*) - U_1(X^*, Y^*)] &= (1 - p) \frac{A_1(1 - A_1) - A_1^2}{A_1^2 + A_1(1 - A_1)} + pv \frac{A_1(\sqrt{v} - A_1) - A_1^2}{A_1^2 + A_1(\sqrt{v} - A_1)} \\ &= (1 - p)p(1 - \sqrt{v})^2 \\ &> 0. \end{aligned}$$

And if $v > (1 + p)^2 / p^2$, then

$$\begin{aligned} 2[U_2(X^*, Y^*) - U_1(X^*, Y^*)] &= -(1 - p) + pv \frac{A_2(\sqrt{v} - A_2) - A_2^2}{A_2^2 + A_2(\sqrt{v} - A_2)} \\ &= \frac{1 - p}{p + 1} (p(v - 1) - 1) \\ &> \frac{1 - p}{p} \\ &> 0. \end{aligned}$$

That is, the payoff of the informed player is greater than that of the uninformed player. (We show in Proposition 5 below the information advantage is always rewarded in a common-value Tullock contest, regardless of the number of players and the number of states of nature.)

Under symmetric information the equilibrium total effort in a Tullock contest is $E(V)/2 > \max\{2A_1^2, 2A_2^2\}$, i.e., the total effort when player 2 has an information advantage is less than when both players have the same information.

In an all pay auction in which player 2 observes the value but player 1 does not, the equilibrium total effort is

$$TE^{APA} = 2(1 - p)p + (1 - p)^2 + p^2v = (1 - p)(1 + p) + p^2v.$$

As we showed above, if $v \leq (1 + p)^2 / p^2$, then the expected total effort in the unique equilibrium of the Tullock contest, which is interior, is $TE = 2A_2^2 = [1 - p(1 - \sqrt{v})]^2 / 2$. Hence

$$TE^{APA} - TE = (1 - p)(1 + p) + p^2v - \frac{(1 - p(1 - \sqrt{v}))^2}{2} > 2p > 0.$$

However, if $v > (1 + p)^2 / p^2$, then the expected total effort in the unique equilibrium of the Tullock contest, which is a corner equilibrium, is $TE = 2p^2v / (1 + p)^2$. Assume that $p = 1/4$. Then

$$TE^{APA} - TE = \frac{15}{16} - \frac{7}{400}v.$$

Hence $TE^{APA} < TE$ for $v > 375/7$.

5 n -Player Common-Value Tullock Contests

The following result is a direct implication of the theorem of Einy, Moreno and Shitovitz (2002).

Theorem 2. *Let $X^* = (X_1^*, \dots, X_n^*)$ be any equilibrium of an n -player common-value Tullock contest. If player i has an information advantage over player j , then $U_i(X^*) \geq U_j(X^*)$.*

Proof. An n -player common-value Tullock contest $(N, (\Omega, p), (\Pi_i)_{i \in N}, V)$ is formally identical to what Einy, Moreno and Shitovitz (2002) refer to as an oligopolist industry $(N, (\Omega, p), P, c, (\Pi_i)_{i \in N})$, where the demand and cost functions are defined for $(\omega, x) \in \Omega \times \mathbb{R}_{++}$ as

$$P(\omega, q) = \frac{V(\omega)}{x},$$

and

$$c(\omega, x) = x,$$

respectively. With this convention, the profit of firm $i \in N$ in the industry coincides with the expected payoff of player $i \in N$ in the contest, i.e., for $\omega \in \Omega$ and $X \in S$,

$$\begin{aligned} u_i(\omega, X) &= \frac{V(\omega)}{\sum_{s=1}^n X_s} X_i(\omega) - X_i(\omega) \\ &= P(\omega, \sum_{s=1}^n X_s(\omega)) X_i(\omega) - c(\omega, X_i(\omega)). \end{aligned}$$

Theorem 2 then follows from the theorem of Einy, Moreno and Shitovitz (2002). ■

The following example shows that Proposition 2 does not extend to common-value Tullock contests with more than two players. In the example, player 1 has only the prior information whereas players 2 and 3 have complete information. In equilibrium

the expected effort of the uninformed player is below that of each of the informed players.

Example 2. Consider a 3-player common-value Tullock contest in which $m = 2$, $p_1 = p_2 = 1/2$, $v_1 = 1$ and $v_2 = 2$. Player 1 has no information, i.e., his information partition is $\Pi_1 = \{\omega_1, \omega_2\}$, and players 2 and 3 have complete information, i.e., their information partitions are $\Pi_2 = \Pi_3 = \{\{\omega_1\}, \{\omega_2\}\}$. In the interior equilibrium of this contest, which is readily calculated by solving the system of equations formed by the players' reaction functions, the effort of player 1 is $X_1^* = (0.30899, 0.30899)$ while the efforts of players 2 and 3 are $X_2^* = X_3^* = (0.20342, 0.46933)$. Note that

$$E(X_1^*) = 0.30899 < \frac{1}{2}(0.20342 + 0.46933) = E(X_2^*) = E(X_3^*),$$

i.e., the expected effort of player 1 is less than the expected effort of players 2 and 3.

The next example shows that Proposition 3 does not extend to contests with more than two players. In the example there is an informed player and a number of uninformed players. Contrary to the natural extension of Proposition 3, the ex-ante probability that the informed player wins the prize is above that of the uninformed players.

Example 3. Consider an eight player common-value Tullock contest in which $m = 2$, $p_1 = p_2 = 1/2$, $v_1 = 1$ and $v_2 = 2$. Players 1 to 7 have no information, i.e., their information partition is $\Pi_i = \{\omega_1, \omega_2\}$ for $i \in \{1, \dots, 7\}$, and player 8 is completely informed, i.e., his information partitions is $\Pi_8 = \{\{\omega_1\}, \{\omega_2\}\}$. This contest has a (corner) equilibrium given by

$$X_1^* = \dots = X_7^* = (0.15551, 0.15551), \quad X_8^* = (0, 0.38694).$$

In equilibrium, the ex-ante probability that player $i \in \{1, 2, \dots, 7\}$ wins the prize is

$$\bar{p}_i^* = \frac{1}{2} \left(\frac{1}{7} + \frac{0.15551}{7(0.15551) + 0.38694} \right) = 0.12413,$$

whereas the ex-ante probability that player 8 win the prize is

$$\bar{p}_8^* = 1 - 7(0.12413) = 0.13109.$$

Thus, the informed player wins the prize more frequently than an uninformed player.

6 Concluding remarks

Under broad conditions, Tullock contests have pure strategy equilibria. Two-player common-value Tullock contests in which one player has an information advantage exhibit interesting properties: equilibrium is unique, although it may not be interior. And whether the equilibrium is interior or not, the player with an information advantage exerts the same expected effort as his opponent, but obtains a greater payoff and wins the object less frequently. When the equilibrium is interior, i.e., when the distribution of the players' common value is not too disperse, the players exert less effort than when they are symmetrically informed. (It is an open question whether this property holds when the distribution of values is sufficiently disperse that the unique equilibrium is a corner equilibrium.) While the information advantage is rewarded in common-value Tullock contests whether there are two or more players, the other properties of equilibrium obtained for two-player contests may not hold for contests with more than two players. Interestingly, a Tullock contest does not necessarily generates less effort than an all-pay auction.

7 Appendix

Proof of Theorem 1. Let $(N, (\Omega, p), \{\Pi_i\}_{i \in N}, \{V_i\}_{i \in N}, \{c_i\}_{i \in N})$ be a Tullock contest. Since the cost function of each player is strictly increasing and convex in the player's effort, it follows from (1) that there exists $Q > 0$ such that $u_i(\cdot, x) < 0$ for every $i \in N$ and every $x \in \mathbb{R}_+^n$, provided $x_i > Q$. For any $0 < \varepsilon < Q$ consider a variant of the contest, denoted by G_ε , in which the effort set of each player i is restricted to be the bounded interval $[\varepsilon, Q]$. In G_ε , the set of strategies of player i , $S_{i,\varepsilon}$, is identifiable with the compact set $[\varepsilon, Q]^{\Pi_i}$ via the bijection $\mathbf{x}_i \longleftrightarrow (\mathbf{x}_i(\pi_i))_{\pi_i \in \Pi_i}$. Player i 's expected payoff function U_i is continuous on $S_\varepsilon = \times_{i=1}^n S_{i,\varepsilon}$ (since the success function ρ in (4) is continuous if efforts are restricted to $[\varepsilon, Q]$), and it is concave in i 's own strategy (as the state-dependent payoff function $u_i(\cdot, x)$ is concave in the variable x_i if efforts are restricted to $[\varepsilon, Q]$). Nash's Theorem thus guarantees existence of a Bayesian equilibrium in G_ε ; pick one such equilibrium and denote it by $X_\varepsilon^* = (X_{1,\varepsilon}^*, \dots, X_{n,\varepsilon}^*)$.

We will now show that

$$\liminf_{\varepsilon \rightarrow 0+} \bar{X}_\varepsilon^*(\cdot) > 0.$$

Indeed, suppose to the contrary that there is a vanishing positive sequence $\{\varepsilon_k\}_{k=1}^\infty$ such that

$$\min_{\omega \in \Omega} \lim \bar{X}_{\varepsilon_k}^* (\omega) = 0, \quad (6)$$

and fix $\omega^* \in \Omega$ such that

$$\bar{X}_{\varepsilon_k}^* (\omega^*) = \min_{\omega \in \Omega} \bar{X}_{\varepsilon_k}^* (\omega) \quad (7)$$

for infinitely many k (and thus, w.l.o.g., for every k). Since the expected payoff of player i is negative in every state of nature when $x_i = Q$, for any sufficiently small ε_k the equilibrium strategy X_{i,ε_k}^* satisfies $X_{i,\varepsilon_k}^* (\cdot) < Q$. Thus, for a given $\pi_i \in \Pi_i$, $X_i^* (\pi_i) \in [\varepsilon_k, Q)$. Additionally, X_i and $X_i (\pi_i)$ can both be viewed as the argument of the function $U_i(X_{-i,\varepsilon_k}^*, X_i | \pi_i)$, since $X_i (\pi_i)$ is the only numerical input needed to determine the conditional expected payoff of player i given π_i , when the equilibrium strategies of players other than i are X_{-i,ε_k}^* . Since the equilibrium strategy X_{i,ε_k}^* is a (local) maximizer of $U_i(X_{-i,\varepsilon_k}^*, X_i | \pi_i)$ by (3), then

$$\left. \frac{dU_i(X_{-i,\varepsilon_k}^*, X_i | \pi_i)}{dX_i (\pi_i)} \right|_{X_i(\pi_i)=X_{i,\varepsilon_k}^* (\pi_i)} \leq 0.$$

That is,

$$\left. \frac{dE[u_i(\cdot, X_{-i,\varepsilon_k}^* (\cdot), X_i (\pi_i) | \pi_i)]}{dX_i (\pi_i)} \right|_{X_i(\pi_i)=X_{i,\varepsilon_k}^* (\pi_i)} \leq 0,$$

or, equivalently,

$$E \left[\frac{du_i(\cdot, X_{-i,\varepsilon_k}^* (\cdot), X_{i,\varepsilon_k}^* (\pi_i))}{dx_i} | \pi_i \right] \leq 0.$$

Using (4) and (1) we calculate the derivative explicitly,

$$E \left[\frac{V_i(\cdot)}{\bar{X}_{\varepsilon_k}^* (\cdot)} - \frac{X_{i,\varepsilon_k}^* (\pi_i) V_i(\cdot)}{\bar{X}_{\varepsilon_k}^* (\cdot)^2} - \frac{d}{dx_i} c_i (\cdot, X_{i,\varepsilon_k}^* (\pi_i)) | \pi_i \right] \leq 0.$$

Thus

$$E \left[\frac{V_i(\cdot)}{\bar{X}_{\varepsilon_k}^* (\cdot)} - \frac{d}{dx_i} c_i (\cdot, X_{i,\varepsilon_k}^* (\pi_i)) | \pi_i \right] - X_{i,\varepsilon_k}^* (\pi_i) E \left[\frac{V_i(\cdot)}{\bar{X}_{\varepsilon_k}^* (\cdot)^2} | \pi_i \right] \leq 0,$$

which leads to

$$X_{i,\varepsilon_k}^* (\pi_i) \geq \frac{E \left[\frac{V_i(\cdot)}{\bar{X}_{\varepsilon_k}^* (\cdot)} - \frac{d}{dx_i} c_i (\cdot, X_{i,\varepsilon_k}^* (\pi_i)) | \pi_i \right]}{E \left[\frac{V_i(\cdot)}{\bar{X}_{\varepsilon_k}^* (\cdot)^2} | \pi_i \right]}. \quad (8)$$

Inequality (8) holds, in particular, for $\pi_i = \pi_i(\omega^*)$. Since $X_{i,\varepsilon_k}^*(\omega^*) = X_{i,\varepsilon_k}^*(\pi_i(\omega^*))$ (as, by definition, $\omega^* \in \pi_i(\omega^*)$), (8) yields

$$X_{i,\varepsilon_k}^*(\omega^*) \geq \frac{E \left[\frac{V_i(\cdot)}{\bar{X}_{\varepsilon_k}^*(\cdot)} - \frac{d}{dx_i} c_i(\cdot, X_{i,\varepsilon_k}^*(\omega^*)) \mid \pi_i(\omega^*) \right]}{E \left[\frac{V_i(\cdot)}{\bar{X}_{\varepsilon_k}^*(\cdot)^2} \mid \pi_i(\omega^*) \right]}. \quad (9)$$

Summing over $i \in N$ we obtain

$$\bar{X}_{\varepsilon_k}^*(\omega^*) \geq \sum_{i=1}^n \frac{E \left[\frac{V_i(\cdot)}{\bar{X}_{\varepsilon_k}^*(\cdot)} - \frac{d}{dx_i} c_i(\cdot, X_{i,\varepsilon_k}^*(\omega^*)) \mid \pi_i(\omega^*) \right]}{E \left[\frac{V_i(\cdot)}{\bar{X}_{\varepsilon_k}^*(\cdot)^2} \mid \pi_i(\omega^*) \right]},$$

or (since $\bar{X}_{\varepsilon_k}^*(\omega^*) \geq n\varepsilon > 0$)

$$1 \geq \sum_{i=1}^n \frac{E \left[\frac{\bar{X}_{\varepsilon_k}^*(\omega^*)}{\bar{X}_{\varepsilon_k}^*(\cdot)} V_i(\cdot) - \bar{X}_{\varepsilon_k}^*(\omega^*) \frac{d}{dx_i} c_i(\cdot, X_{i,\varepsilon_k}^*(\omega^*)) \mid \pi_i(\omega^*) \right]}{E \left[\frac{\bar{X}_{\varepsilon_k}^*(\omega^*)^2}{\bar{X}_{\varepsilon_k}^*(\cdot)^2} V_i(\cdot) \mid \pi_i(\omega^*) \right]}. \quad (10)$$

By the definition of $\bar{X}_{\varepsilon_k}^*(\omega^*)$ (see (7)),

$$0 \leq \frac{\bar{X}_{\varepsilon_k}^*(\omega^*)}{\bar{X}_{\varepsilon_k}^*(\omega)} \leq 1$$

for every $\omega \in \Omega$. Hence we assume w.l.o.g. (by moving to a subsequence if necessary) that the limit

$$a(\omega) = \lim_{k \rightarrow \infty} \frac{\bar{X}_{\varepsilon_k}^*(\omega^*)}{\bar{X}_{\varepsilon_k}^*(\omega)}$$

exists for every $\omega \in \Omega$. Note also that $a(\omega) = 1$ for $\omega = \omega^*$, which occurs with positive probability by our assumption on p , and thus

$$\lim_{k \rightarrow \infty} E \left[\frac{\bar{X}_{\varepsilon_k}^*(\omega^*)^2}{\bar{X}_{\varepsilon_k}^*(\cdot)^2} V_i(\cdot) \mid \pi_i(\omega^*) \right] = E \left[a(\cdot)^2 V_i(\cdot) \mid \pi_i(\omega^*) \right] > 0. \quad (11)$$

Also, since $dc_i(\cdot, 0)/dx_i$ is well defined (because c_i is concave), then (6) and (7) imply

$$\lim_{k \rightarrow \infty} E \left[\bar{X}_{\varepsilon_k}^*(\omega^*) \frac{dc_i(\cdot, X_{i,\varepsilon_k}^*(\omega^*))}{dx_i} \mid \pi_i(\omega^*) \right] = 0. \quad (12)$$

Taking limit on the right-hand side of (10), which exist by (11) and (12), we get

$$1 \geq \sum_{i=1}^n \frac{E[a(\cdot) V_i(\cdot) \mid \pi_i(\omega^*)]}{E[a(\cdot)^2 V_i(\cdot) \mid \pi_i(\omega^*)]}.$$

Furthermore, as $0 \leq a(\cdot)^2 \leq a(\cdot) \leq 1$, we obtain

$$1 \geq \sum_{i=1}^n \frac{E[a(\cdot) V_i(\cdot) \mid \pi_i(\omega^*)]}{E[a(\cdot)^2 V_i(\cdot) \mid \pi_i(\omega^*)]} \geq n.$$

Since by assumption $n \geq 2$, we have reached a contradiction. This proves that, indeed,

$$\liminf_{\varepsilon \rightarrow 0+} \bar{X}_\varepsilon^*(\cdot) > 0. \quad (13)$$

Now let $\{\varepsilon_k^*\}_{k=1}^\infty$ be a vanishing positive sequence such that the limit

$$X_i^*(\omega) \equiv \lim_{k \rightarrow \infty} X_{i,\varepsilon_k}^*(\omega)$$

exists for every $i \in N$ and $\omega \in \Omega$. (Such a sequence exists since all $X_{i,\varepsilon}^*(\omega)$ belong to the compact interval $[0, Q]$.) Obviously, $X^* = (X_1^*, \dots, X_n^*)$ constitutes a strategy profile in the contest G , and it follows from (13) that

$$\bar{X}^*(\cdot) > 0. \quad (14)$$

We will show that X^* is a Bayesian equilibrium of G .

Since the state-dependent payoff function $u_i(\cdot, x)$ is continuous at any point x with $\bar{x} > 0$, then for every $i \in N$, every $\pi_i \in \Pi_i$, and every sequence $\{Y_k\}_{k=1}^\infty$ of strategy profiles such that $Y_{i,0}(\omega) = \lim_{k \rightarrow \infty} Y_{i,k}(\omega)$ for every i and ω , and $Y_0(\cdot) > 0$, we have

$$\lim_{k \rightarrow \infty} U_i(Y_{1,k}, \dots, Y_{n,k} \mid \pi_i) = U_i(Y_{1,0}, \dots, Y_{n,0} \mid \pi_i). \quad (15)$$

Since every X_ε^* is a Bayesian equilibrium in G_ε , then for every sufficiently large k and every strategy X_i of player i satisfying $0 < X_i(\cdot) \leq Q$ we have

$$U_i(X_{\varepsilon_k}^* \mid \pi_i) \geq U_i(X_{-i,\varepsilon_k}^*, X_i \mid \pi_i). \quad (16)$$

The inequality (14) and equation (15) allow us to apply the limit as $k \rightarrow \infty$ to both sides of inequality (16), which shows that

$$U_i(X^* \mid \pi_i) \geq U_i(X_{-i}^*, X_i \mid \pi_i) \quad (17)$$

for every strategy X_i of player i satisfying $0 < X_i(\cdot) \leq Q$ and every $\pi_i \in \Pi_i$.

It is easy to see that

$$\liminf_{x_i \rightarrow 0+} U_i(X_{-i}^*, x_i, \cdot) \geq U_i(X_{-i}^*, 0 \mid \pi_i),$$

where $x_i > 0$ (respectively, $x_i = 0$) is identified with a strategy of i for which $X_i(\pi_i) = x_i$ (respectively, $X_i(\pi_i) = 0$). Thus (17) in fact holds for every for every strategy X_i satisfying $0 \leq X_i(\cdot) \leq Q$ (i.e., the deviations of i may be zero at some states of nature).

Finally, note that player i can improve upon any strategy X_i for which $X_i(\omega) > Q$ at some ω by lowering the effort on $\pi_i(\omega)$ to zero and thus receiving non-negative expected payoff conditional on $\pi_i(\omega)$. Thus, in contemplating a unilateral deviation from X_i^* , player i is never worse off by limiting himself to strategies X_i satisfying $0 \leq X_i(\cdot) \leq Q$. But this implies that (17) holds for every strategy $X_i \in S_i$. Since this is the case for every $i \in N$, we have shown that X^* is a Bayesian equilibrium of G . ■

Proof of Lemma 1. Assume that $\sqrt{v_{\bar{k}}} \geq A_{\bar{k}}$ for some $\bar{k} < m$.

We show that $\sqrt{v_k} > A_k$ for all $k > \bar{k}$. Suppose not; let $\hat{k} > \bar{k}$ be the first index such that for $\sqrt{v_{\hat{k}}} \leq A_{\hat{k}}$. Since $\sqrt{v_{\hat{k}-1}} \geq A_{\hat{k}-1}$, then

$$\left(1 + \sum_{s=\hat{k}-1}^m p_s\right) \sqrt{v_{\hat{k}-1}} \geq \left(1 + \sum_{s=\hat{k}-1}^m p_s\right) A_{\hat{k}-1} = \sum_{s=\hat{k}-1}^m p_s \sqrt{v_s}.$$

Thus, $v_{\hat{k}} > v_{\hat{k}-1}$ and $\sqrt{v_{\hat{k}-1}} \geq A_{\hat{k}-1}$ imply

$$\begin{aligned} \left(1 + \sum_{s=\hat{k}}^m p_s\right) \sqrt{v_{\hat{k}}} &> \left(1 + \sum_{s=\hat{k}-1}^m p_s\right) \sqrt{v_{\hat{k}-1}} + p_{\hat{k}} \sqrt{v_{\hat{k}}} \\ &\geq \left(1 + \sum_{s=\hat{k}-1}^m p_s\right) A_{\hat{k}-1} + p_{\hat{k}} \sqrt{v_{\hat{k}}} \\ &= \sum_{s=\hat{k}-1}^m p_s \sqrt{v_s} + p_{\hat{k}} \sqrt{v_{\hat{k}}} \\ &= \left(1 + \sum_{s=\hat{k}}^m p_s\right) A_{\hat{k}}, \end{aligned}$$

which contradicts that $\sqrt{v_{\hat{k}}} \leq A_{\hat{k}}$.

Now we show that $A_{\bar{k}} \geq A_k$ for all $k > \bar{k}$. Suppose not; let $\tilde{k} > \bar{k}$ be the first index $k > \bar{k}$ such that $A_{\tilde{k}} < A_k$. Since $A_{\tilde{k}} \geq A_{\tilde{k}-1}$ and $\sqrt{v_{\tilde{k}-1}} \geq A_{\tilde{k}-1}$ (as we have just showed), then

$$\begin{aligned} \left(1 + \sum_{s=\tilde{k}-1}^m p_s\right) A_{\tilde{k}-1} &= \sum_{s=\tilde{k}-1}^m p_s \sqrt{v_s} \\ &= p_{\tilde{k}-1} \sqrt{v_{\tilde{k}-1}} + \sum_{s=\tilde{k}}^m p_s \sqrt{v_s} \\ &\geq p_{\tilde{k}-1} A_{\tilde{k}-1} + \left(1 + \sum_{s=\tilde{k}}^m p_s\right) A_{\tilde{k}}. \end{aligned}$$

Hence

$$\left(1 + \sum_{s=\tilde{k}-1}^m p_s\right) A_{\tilde{k}-1} - p_{\tilde{k}-1} A_{\tilde{k}-1} \geq \left(1 + \sum_{s=\tilde{k}}^m p_s\right) A_{\tilde{k}},$$

i.e.,

$$\left(1 + \sum_{s=\tilde{k}}^m p_s\right) A_{\tilde{k}-1} \geq \left(1 + \sum_{s=\tilde{k}}^m p_s\right) A_{\tilde{k}}.$$

Thus, $A_{\bar{k}} \geq A_{\tilde{k}-1} \geq A_{\tilde{k}}$, which yields a contradiction. ■

Proof of Proposition 1. Let (X, Y) , where $X = (x, \dots, x)$ and $Y = (y_1, \dots, y_m)$, be a Bayesian equilibrium. It is easy to see that $x + y_s > 0$ for all $s \in \{1, \dots, m\}$: If $x + y_s = 0$ for some $s \in \{1, \dots, m\}$, since $\rho_i^T(0) < 1$ for some $i \in \{1, 2\}$, then player i by exerting an arbitrarily small effort $\varepsilon > 0$ wins the prize with probability one when the state is ω_s , and therefore can profitably deviate.

Moreover, since x maximizes player 1's payoff given Y , then

$$\sum_{s=1}^m p_s v_s \frac{y_s}{(x + y_s)^2} - 1 \leq 0, \quad (18)$$

holds (with equality if $x > 0$). And since y_s maximizes player 2's payoff in state ω_s given x , then

$$v_s \frac{x}{(x + y_s)^2} - 1 \leq 0, \quad (19)$$

holds (with equality if $y_s > 0$) for each $s = 1, \dots, m$.

We show that $x > 0$. If $y_k = 0$ for some k , then $x > 0$, since as shown above $x + y_k > 0$ for all k . If $y_k > 0$ for some k , then $y_k = \sqrt{x} (\sqrt{v_k} - \sqrt{x}) > 0$ by (19), which implies $x > 0$. Thus, in either case $x > 0$.

We show that if $y_k > 0$ for some $k < m$, then $y_{k'} > 0$ for all $k' > k$. Since $x > 0$, if $y_k > 0$, then $y_k = \sqrt{x}(\sqrt{v_k} - \sqrt{x})$ by (19), and since $v_{k'} > v_k$ for all $k' > k$, then $\sqrt{x}(\sqrt{v_{k'}} - \sqrt{x}) > 0$, i.e.,

$$v_{k'} \frac{x}{x^2} - 1 > 0,$$

for all $k' > k$. Then $y_{k'} = 0$ would violate the inequality (19) for $s = k'$. Hence $y_{k'} > 0$.

Let k° be the smallest index such that $y_k \geq 0$. Therefore $x > 0$ and (18) imply

$$\sum_{s=1}^m p_s v_s \frac{y_s}{(x + y_s)^2} = \sum_{s=k^\circ}^m p_s v_s \frac{y_s}{(x + y_s)^2} = 1,$$

and (19) implies $y_{k'} = \sqrt{x}(\sqrt{v_{k'}} - \sqrt{x}) > 0$ for all $k' \geq k^\circ$. Hence $x = A_{k^\circ}^2$, $y_k = A_{k^\circ}(\sqrt{v_{k^\circ}} - A_{k^\circ})$ for all $k \geq k^\circ$, and $y_k = 0$ for all $k < k^\circ$.

We show that $k^\circ = k^*$, which establishes that the profile $(x^*, y_1^*, \dots, y_m^*)$ identified in Proposition 1 is the unique equilibrium. Clearly $k^\circ \geq k^*$: If $k^\circ < k^*$, since k^* is the smallest index such that $\sqrt{v_k} \geq A_k$, then $\sqrt{v_{k^\circ}} < A_{k^\circ}$, and therefore $y_{k^\circ} = \sqrt{x}(\sqrt{v_{k^\circ}} - \sqrt{x}) = A_{k^\circ}(\sqrt{v_{k^\circ}} - A_{k^\circ}) < 0$, which contradicts that k° satisfies $y_{k^\circ} \geq 0$. Assume that $k^\circ > k^*$. Therefore $y_{k^*} = 0$. Since $\sqrt{v_{k^*}} \geq A_{k^*}$, then $A_{k^*}^2 \geq A_{k^\circ}^2 = x$ by Lemma 1, and therefore

$$v_{k^*} \frac{x}{x^2} - 1 = \frac{A_{k^\circ}^2}{A_{k^\circ}^4} (v_{k^*} - A_{k^\circ}^2) > 0.$$

Hence $y_{k^*} = 0$ violates the inequality (19) for $s = k^*$. ■

Proof of Proposition 3. Let us be given a two-player common-value Tullock contest in which player 2 has an information advantage over player 1. Given $(y_{k^*}, \dots, y_m) \in \mathbb{R}_+^{k^*}$ define the function

$$\bar{p}_2(y_{k^*}, \dots, y_m) := \sum_{k=k^*}^m \frac{p_k y_k}{y_k + \sum_{s=k^*}^m p_s y_s}.$$

Hence $\bar{\rho}_2 = \bar{p}_2(y_{k^*}^*, \dots, y_m^*)$. We show that the maximum value of \bar{p}_2 on $K = \{(y_{k^*}, \dots, y_m) \in \mathbb{R}_+^{k^*} \mid y_{k^*} \leq y_{k^*+1} \leq \dots \leq y_m\}$ is reached at $y_{k^*} = \dots = y_m$. Hence

$$\max_K \bar{p}_2 = \sum_{k=k^*}^m \frac{p_k}{1 + \sum_{s=k^*}^m p_s} \leq \frac{1}{2},$$

and therefore $y_{k^*}^* < \dots < y_m^*$ implies $\bar{\rho}_2 = \bar{p}_2(y_{k^*}^*, \dots, y_m^*) < \max_K \bar{p}_2 \leq 1/2$, which establishes Proposition 3.

Differentiating \bar{p}_2 with respect to y_k for $k \in \{k^*, \dots, m\}$ we get

$$\frac{\partial \bar{p}_2}{\partial y_k} = p_k \left(\sum_{t=k^*, t \neq k}^m \frac{p_t y_t}{(y_k + \sum_{s=k^*}^m p_s y_s)^2} - \sum_{t=k^*, t \neq k}^m \frac{p_t y_t}{(y_t + \sum_{s=k^*}^m p_s y_s)^2} \right), \quad (20)$$

Hence $y_{k^*} = \dots = y_m$ implies

$$\frac{\partial \bar{p}_2}{\partial y_k} = 0$$

for all $k \in \{k^*, \dots, m\}$. Moreover, for every $(y_{k^*}, \dots, y_m) \in K$ such that $y_{k^*} \leq y_{k^*+1} \leq \dots \leq y_m$, then $\partial \bar{p}_2 / \partial y_{k^*} > 0$, and therefore $y_{k^*} = y_{k^*+1}$. Suppose now that $y_{k^*} = y_{k^*+1} = \dots = y_k = y$, $m-1 \geq k > 1$. We will show that $y_{k+1} = y$ as well. If $y_{k^*} = y_{k^*+1} = \dots = y_k$, then by (20) we obtain that $\partial \bar{p}_2 / \partial y_k > 0$, and therefore $y_k = y_{k+1}$. ■

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